

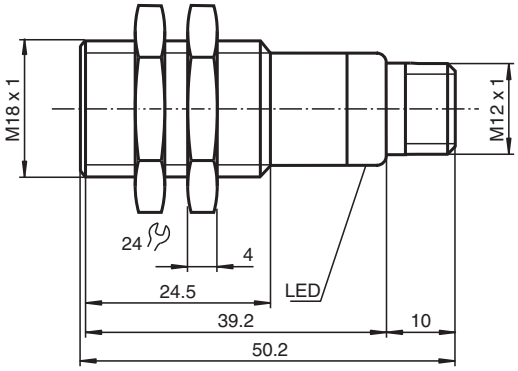
Ultrasonic sensor

UB300-18GM40-I-V1

- Short design, 40 mm
- Function indicators visible from all directions
- Analog output 4 mA ... 20 mA
- Measuring window adjustable
- Program input
- Temperature compensation

Single head system

Dimensions



Technical Data

General specifications		
Sensing range		35 ... 300 mm
Adjustment range		50 ... 300 mm
Dead band		0 ... 35 mm
Standard target plate		100 mm x 100 mm
Transducer frequency		approx. 390 kHz
Response delay		approx. 50 ms
Indicators/operating means		
LED green		Power on

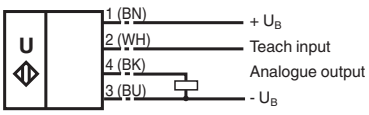
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Technical Data

LED yellow		solid yellow: object in the evaluation range yellow, flashing: program function, object detected
LED red		solid red: Error red, flashing: program function, object not detected
Electrical specifications		
Operating voltage	U_B	10 ... 30 V DC , ripple 10 %$_{SS}$
No-load supply current	I_0	≤ 20 mA
Input		
Input type		1 program input lower evaluation limit A1: -U_B ... +1 V, upper evaluation limit A2: +4 V ... +U_B input impedance: > 4.7 kΩ, pulse duration: ≥ 1 s
Output		
Output type		1 analog output 4 ... 20 mA, short-circuit/overload protected
Default setting		evaluation limit A1: 50 mm evaluation limit A2: 300 mm
Resolution		0.4 mm at max. sensing range
Deviation of the characteristic curve		± 1 % of full-scale value
Repeat accuracy		± 0.5 % of full-scale value
Load impedance		0 ... 300 Ohm
Temperature influence		± 1.5 % of full-scale value
Compliance with standards and directives		
Standard conformity		
Standards		EN IEC 60947-5-2:2020 IEC 60947-5-2:2019 EN 60947-5-7:2003 IEC 60947-5-7:2003
Approvals and certificates		
UL approval		cULus Listed, Class 2 Power Source
CCC approval		CCC approval / marking not required for products rated ≤36 V
Ambient conditions		
Ambient temperature		-25 ... 70 °C (-13 ... 158 °F)
Storage temperature		-40 ... 85 °C (-40 ... 185 °F)
Mechanical specifications		
Connection type		Connector plug M12 x 1 , 4-pin
Housing diameter		18 mm
Degree of protection		IP67
Material		
Housing		brass, nickel-plated
Transducer		epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT
Mass		25 g

Connection

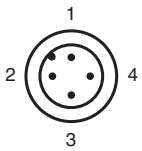
Standard symbol/Connections:
(version I)



Core colours in accordance with EN 60947-5-2.

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Connection Assignment

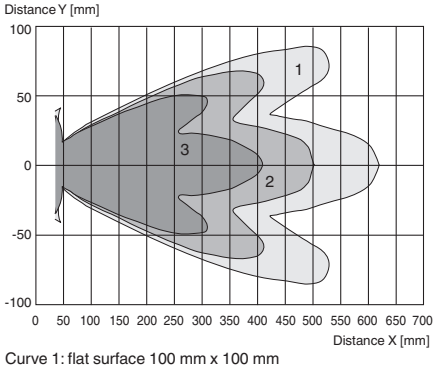


Wire colors in accordance with EN 60947-5-2

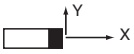
1	BN	(brown)
2	WH	(white)
3	BU	(blue)
4	BK	(black)

Characteristic Curve

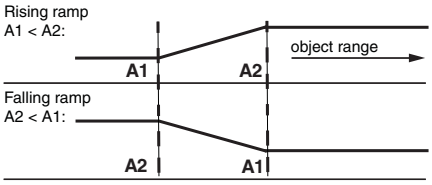
Characteristic response curve



Curve 1: flat surface 100 mm x 100 mm
Curve 2: flat surface 10 mm x 10 mm
Curve 3: round bar, Ø 25 mm



Programming the analog output mode



Accessories

	**UB-PROG2**	Programming unit
	**OMH-04**	Mounting aid for round steel ø 12 mm or sheet 1.5 mm ... 3 mm

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Accessories

	**BF 18**	Mounting flange, 18 mm
	**BF 18-F**	Plastic mounting adapter, 18 mm
	**BF 5-30**	Universal mounting bracket for cylindrical sensors with a diameter of 5 ... 30 mm
	**V1-G-2M-PVC**	Female cordset single-ended M12 straight A-coded, 4-pin, PVC cable grey
	**V1-W-2M-PUR**	Female cordset single-ended M12 angled A-coded, 4-pin, PUR cable grey
	**UVW90-K18**	Ultrasonic -deflector
	**M18K-VE**	Plastic nuts with centering ring for the vibration-free mounting of cylindrical sensors

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Programming

Programming procedure

The sensor features a programmable analog output with two programmable evaluation boundaries. Programming the evaluation boundaries and the operating mode is done by applying the supply voltage $-U_B$ or $+U_B$ to the Teach-In input. The supply voltage must be applied to the Teach-In input for at least 1 s. LEDs indicate whether the sensor has recognized the target during the programming procedure.

Note:

Evaluation boundaries may only be specified directly after Power on. A time lock secures the adjusted switching points against unintended modification 5 minutes after Power on. To modify the evaluation boundaries later, the user may specify the desired values only after a new Power On.

Note:

If a programming adapter UB-PROG2 is used for the programming procedure, button A1 is assigned to $-U_B$ and button A2 is assigned to $+U_B$.

Programming the analog output

Rising ramp

1. Place the target at the near end of the desired evaluation range
2. Program the evaluation boundary by applying $-U_B$ to the Teach-In input (yellow LED flashes)
3. Disconnect the Teach-In input from $-U_B$ to save the evaluation boundary
4. Place the target at the far end of the desired evaluation range
5. Program the evaluation boundary by applying $+U_B$ to the Teach-In input (yellow LED flashes)
6. Disconnect the Teach-In input from $+U_B$ to save the evaluation boundary

Falling ramp

1. Place the target at the far end of the desired evaluation range
2. Program the evaluation boundary by applying $-U_B$ to the Teach-In input (yellow LED flashes)
3. Disconnect the Teach-In input from $-U_B$ to save the evaluation boundary
4. Place the target at the near end of the desired evaluation range
5. Program the evaluation boundary by applying $+U_B$ to the Teach-In input (yellow LED flashes)
6. Disconnect the Teach-In input from $+U_B$ to save the evaluation boundary

Installation Conditions

If the sensor is installed at places, where the environment temperature can fall below 0 °C, for the sensors fixation, one of the mounting flanges BF18, BF18-F or BF 5-30 must be used.
In case of direct mounting of the sensor in a through hole using the steel nuts, it has to be fixed at the middle of the housing thread. If a fixation at the front end of the threaded housing is required, plastic nuts with centering ring (accessories) must be used.

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